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MANIPULATOR FOR FERROMAGNETIC ROLLED STEEL DEPOT

BY

***L. CIOBANU**

Abstract. The paper present a TT manipulator for manipulation in depot of ferromag-netic rolled-steel of different shape and dimensions, stored on the racks. For bringing up-to-date and delivery the rolled steel use the direct drive the rolled steel by modules of bilateral linear induction motor placed along the guided roller.

Keywords: manipulator, robot.