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# THE COMPLEX TRANSFER IMPEDANCE OF A LINEAR TWO-PORT WITH NON-LINEAR RECEIVER 

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#### Abstract

The nonlinear differential equation of first order is established, satisfied by the function $X_{2}\left(R_{2}\right)$, where $\underline{Z}_{2}=R_{2}+\mathrm{j} X_{2}$ is the complex impedance of the nonlinear inertial and passive receiver of a linear and non-autonomous in restreint sens two-port, in harmonic steady-state, so that the complex transfer impedance of the two-port have an extreme value.

The established differential equation is integrated analytically in two particular cases, when this one is of Bernoully type.

Key words: in restreint sense linear and non-autonomous two-ports; nonlinear inertial and passive receiver; complex transfer impedance; nonlinear differential equation of first order.


## 1. Introduction

It is well known that in the theory of the linear and non-autonomous in restreint sens two-ports, having the eqs.

$$
\left[\begin{array}{l}
\underline{U}_{1}  \tag{1}\\
\underline{I}_{1}
\end{array}\right]=[\underline{A}]\left[\begin{array}{l}
\underline{U}_{2} \\
\underline{I}_{2}
\end{array}\right],
$$

with

[^0]\[

[A]=\left[$$
\begin{array}{ll}
\underline{A}_{11} & \underline{A}_{12}  \tag{2}\\
\underline{A}_{21} & \underline{A}_{22}
\end{array}
$$\right]
\]

- the fundamental parameters matrix, may be defined, anmeng other transfer coefficients (Şora, 1964), the transfer complex impedance

$$
\begin{equation*}
\underline{Z}_{m}=\frac{\underline{U}_{2}}{\underline{I}_{1}}=R_{m}+\mathrm{j} X_{m} \tag{3}
\end{equation*}
$$

In what follows a detailed study of this complex impedance is performed, when the two-port's receiver is a nonlinear inertial one. It is a matter of a linear non-autonomous (in restreint sense) two-port (LNT), supplied at the (1), ( $l^{\prime}$ ) gate with a harmonic voltage having a nonlinear inertial and passive receiver (NIPR) represented in Fig. 1. The receiver's complex impedance is

$$
\begin{equation*}
\underline{Z}_{2}=\frac{\underline{U}_{2}}{\underline{I}_{2}}=R_{2}+\mathrm{j} X_{2} . \tag{4}
\end{equation*}
$$



Fig. 1
As it is known (Philippow, 1963), if a nonlinear inertial element is excited with a harmonic signal, the response signal is harmonic too, so that the element's steady-state is a harmonic one, being possible, in this case, to utilize, in an advantageous manner, the symbolic proceeding utilizing complex quantities.

## 2. Utilized Method

The nonlinear inertial character of the complex impedance, $\underline{Z}_{2}$, can be render evident considering both this impedance and hers components, $R_{2}$ and $X_{2}$, as being functions of the amplitude, $I_{m}$, of an arbitrary harmonic current $\left(I_{m}\right)$, as was considered in a previous paper (Rosman, 2005). Consequently relation (4) may be written

$$
\begin{equation*}
\underline{Z}_{2}\left(I_{m}\right)=R_{2}\left(I_{m}\right)+\mathrm{j} X_{2}\left(I_{m}\right) . \tag{5}
\end{equation*}
$$

Simultaneously with complex impedance, $\underline{Z}_{2}$, the signals on the two-port's gates become also functions of amplitude $I_{m}$, namely $\underline{I}_{1}\left(I_{m}\right), \underline{U}_{2}\left(I_{m}\right), \underline{I}_{2}\left(I_{m}\right)$, so that the
transfer complex impedance (3) may be written

$$
\begin{equation*}
\underline{Z}_{m}\left(I_{m}\right)=\frac{\underline{U}_{2}\left(I_{m}\right)}{\underline{I}_{1}\left(I_{m}\right)}=R_{m}\left(I_{m}\right)+\mathrm{j} X_{m}\left(I_{m}\right) . \tag{6}
\end{equation*}
$$

Having in view two-port's eqs. (1) expression (6) becomes

$$
\underline{Z}_{m}\left(I_{m}\right)=\frac{\underline{Z}_{2}\left(I_{m}\right)}{\underline{A}_{21} \underline{Z}_{2}\left(I_{m}\right)+\underline{A}_{22}} .
$$

Evidently it is possible to consider, for simplicity, that $I_{m}=I_{2 m}$.
In what follows the possibility that, in certain conditions, the modulus of complex transfer impedance, $Z_{2 m}$, have extreme values, is studied. Similar studies concerning tha functions $\underline{k}_{U}\left(I_{m}\right)$ and $\underline{k}_{l}\left(I_{m}\right)$ moduli were performed in previous papers (Rosman, 2006, 2012), where $\underline{k}_{U}$ is the voltage transfer coefficient and $\underline{k}_{I}-$ the current transfer coefficient.

## 3. Differential Equation Satisfied by Function $X_{2}\left(R_{2}\right)\left(\right.$ or $\left.R_{2}\left(X_{2}\right)\right)$

Beforhand it is necessary to have in view that unlike the case when the LNT's receiver is linear, the complex transfer impedance being a function of two independent variables, $R_{2}$ and $X_{2}$, when the LNT's receiver is non-linear inertial, this modulus is a function of a single independent variable, namely $I_{m}$.

If notations

$$
\begin{equation*}
x=R_{2}\left(I_{m}\right), \quad y=X_{2}\left(I_{m}\right) \tag{8}
\end{equation*}
$$

are introduced and taking into account relation (5), expression (7) becomes

$$
\begin{equation*}
\underline{Z}_{m}\left(I_{m}\right)=\frac{x\left(I_{m}\right)+\mathrm{j} y\left(I_{m}\right)}{\underline{A}_{21}\left[x\left(I_{m}\right)+\mathrm{j} y\left(I_{m}\right)\right]+\underline{A}_{12}} . \tag{9}
\end{equation*}
$$

The complex transfer impedance's modulus is

$$
\begin{equation*}
Z_{m}\left(I_{m}\right)=\sqrt{\frac{x^{2}+y^{2}}{A_{21}^{2}\left(x^{2}+y^{2}\right)+2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x-2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) y+A_{22}^{2}}} . \tag{10}
\end{equation*}
$$

Having in view that $x$ and $y$ are functions of $I_{m}$ it results that the derivative of expression (10) with respect to $I_{m}$ is

$$
\begin{align*}
& \frac{\mathrm{d} Z_{m}}{\mathrm{~d} I_{m}}=\left(x^{2}+y^{2}\right)^{-1 / 2}\left[A_{21}^{2}\left(x^{2}+y^{2}\right)+2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x-2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) y+A_{22}^{2}\right]^{-3 / 2} \times \\
& \times\left\{\left[2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\left(x^{2}-y^{2}\right)-2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x y+A_{22}^{2} x\right] \frac{\mathrm{d} x}{\mathrm{~d} I_{m}}+\right.  \tag{11}\\
&\left.+\left[2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\left(x^{2}-y^{2}\right)+2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x y+A_{22}^{2} y\right] \frac{\mathrm{d} y}{\mathrm{~d} I_{m}}\right\} .
\end{align*}
$$

Annulling this derivative it results the following differential eq.:

$$
\begin{equation*}
\frac{\mathrm{d} y}{\mathrm{~d} x}+\frac{\mathfrak{R} e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\left(x^{2}+y^{2}\right)-2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x y+A_{22}^{2} x}{\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\left(x^{2}-y^{2}\right)+2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right) x y+A_{22}^{2} y}=0 . \tag{12}
\end{equation*}
$$

Using the notations

$$
\begin{equation*}
\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=\alpha, \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=\beta, A_{22}^{2}=\gamma \tag{13}
\end{equation*}
$$

the differential eq. (12) becomes

$$
\begin{equation*}
\frac{\mathrm{d} y}{\mathrm{~d} x}+\frac{\alpha\left(x^{2}+y^{2}\right)-2 \beta x y+\gamma x}{\beta\left(x^{2}-y^{2}\right)+2 \alpha x y+\gamma y}=0 . \tag{14}
\end{equation*}
$$

## 4. Integration of Differential Equation (14)

Differential eq. (14), of first order, belongs to the type

$$
\begin{equation*}
P(x, y) \mathrm{d} x+Q(x, y) \mathrm{d} y=0, \tag{15}
\end{equation*}
$$

where

$$
\begin{equation*}
P(x, y)=\alpha\left(x^{2}+y^{2}\right)-2 \beta x y+\gamma x, Q(x, y)=\beta\left(x^{2}-y^{2}\right)+2 \alpha x y+\gamma y . \tag{16}
\end{equation*}
$$

Accordingly

$$
\begin{equation*}
\frac{\partial P}{\partial y}=-2(\beta x+\alpha y), \quad \frac{\partial Q}{\partial x}=2(\beta x+\alpha y), \tag{17}
\end{equation*}
$$

so $\partial P / \partial y \neq \partial Q / \partial x$ and, consequently, expression (15) not represents an exact total differential. It results that isn't possible to integrate the differential eq. (14), in general case, than with numerical methods.

### 4.1. Particular Cases

In the particular cases when either $\alpha=0$, or $\beta=0$, the differential eq. (14) becomes more simple, here integration being possible using analytical proceedings.
a) Case $\alpha=0\left(\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=0\right)$. This particular situation takes place when $P_{20}=0$; representing the LNT through the equivalent scheme in T as in Fig. 2, the case $\alpha=0$ is realized when the complex impedances $\underline{\zeta}_{2}$ and $\underline{\zeta}_{3}$ are pure reactive. In this case differential eq. (14) becomes

$$
\begin{equation*}
\frac{\mathrm{d} y}{\mathrm{~d} x}=\frac{x(2 \beta y-\gamma)}{\beta\left(x^{2}-y^{2}\right)+\gamma y} \tag{18}
\end{equation*}
$$



Fig. 2
Performing the dependent variable changing

$$
\begin{equation*}
2 \beta y-\gamma=z \tag{19}
\end{equation*}
$$

differential eq. (18) becomes

$$
\begin{equation*}
\frac{\mathrm{d} z}{\mathrm{~d} x}=\frac{8 \beta^{2} x z}{4 \beta^{2} x^{2}-z^{2}+\gamma^{2}} \tag{20}
\end{equation*}
$$

The integration of this eq. is simpler when this one is written as

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} z}=\frac{4 \beta^{2} x^{2}-z^{2}+\gamma^{2}}{8 \beta^{2} x z}=\frac{1}{2} \cdot \frac{x}{z}-\frac{z^{2}-\gamma^{2}}{8 \beta^{2} x z} \tag{21}
\end{equation*}
$$

belonging to Bernoulli type (Corduneanu, 1981), having the general form

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} z}=m(z) x+n(z) x^{p}, x \in \mathfrak{I}, \tag{22}
\end{equation*}
$$

with

$$
\begin{equation*}
m(z)=\frac{1}{2 z}, n(z)=\frac{z^{2}-\gamma^{2}}{8 b^{2} z}, p=-1 \tag{23}
\end{equation*}
$$

the functions $m(z), n(z)$ being continuous in range $\mathfrak{I}$.

In view to integrate differential eq. (21), this one is divided by $x$ and the dependent variable changing

$$
\begin{equation*}
x^{2}=\lambda \tag{24}
\end{equation*}
$$

is performed so that eq. (21) becomes

$$
\begin{equation*}
\frac{\mathrm{d} \lambda}{\mathrm{~d} z}=\frac{\lambda}{z}-\frac{z^{2}-\gamma^{2}}{4 \beta^{2} z} \tag{25}
\end{equation*}
$$

that is a linear differential eq. having the form

$$
\begin{equation*}
\frac{\mathrm{d} \lambda}{\mathrm{~d} z}+M(z) \lambda+N(z)=0 \tag{26}
\end{equation*}
$$

having the solution (Corduneanu, 1981)

$$
\begin{equation*}
\lambda(z)=\mathrm{e}^{-\int M(z) \mathrm{d} z}\left[C-\int N(z) \mathrm{e}^{\int M(z) \mathrm{d} z} \mathrm{~d} z\right], \tag{27}
\end{equation*}
$$

where

$$
\begin{equation*}
M(z)=\frac{\lambda}{z}, \quad N(z)=\frac{z^{2}-\gamma^{2}}{4 \beta^{2} z} \tag{28}
\end{equation*}
$$

and $C$ is an integration constant.
Differential eq.'s solution (27) can be written as

$$
\begin{equation*}
\lambda(z)=C z-\frac{1}{4 \beta^{2}}\left(z^{2}+\gamma^{2}\right) . \tag{29}
\end{equation*}
$$

Having in view relations (19) and (24) expression (29) becomes

$$
\begin{equation*}
x=\sqrt{C(2 \beta y-\gamma)-\frac{1}{4 \beta^{2}}\left[(2 \beta y-\gamma)^{2}+\gamma^{2}\right]} . \tag{30}
\end{equation*}
$$

Since $x$ represents a resistance (see rel. (8)) it is necessary that the inequality

$$
\begin{equation*}
C(2 \beta y-\gamma)-\frac{1}{4 \beta^{2}}\left[(2 \beta y-\gamma)^{2}+\gamma^{2}\right] \geq 0 \tag{31}
\end{equation*}
$$

be satisfied, which may be written as

$$
\begin{equation*}
y^{2}-\left(2 \beta C+\frac{\gamma}{\beta}\right)-\gamma C+\frac{\gamma^{2}}{2 \beta^{2}} \leq 0 \tag{32}
\end{equation*}
$$

The trinomial's roots from the right side of inequality(32) are

$$
\begin{equation*}
y^{\prime}, y^{\prime \prime}=\beta C+\frac{\gamma}{2 \beta} \pm \frac{1}{2} \sqrt{2 \beta^{2} C^{2}-\frac{\gamma^{2}}{\beta^{2}}} . \tag{33}
\end{equation*}
$$

As regards the integration constant, $C$, this one must satisfy the supplementary inequality

$$
\begin{equation*}
C \geq \frac{\gamma}{2 \beta^{2}}>0 \tag{34}
\end{equation*}
$$

where relation $\left(13_{3}\right)$ was taken into accont.
It is advantageous to write relation (30) as

$$
\begin{equation*}
x^{2}+y^{2}-\left(2 \beta C+\frac{\gamma}{\beta}\right) y+\frac{\gamma^{2}}{2 \beta^{2}}+C \gamma \geq 0 \tag{35}
\end{equation*}
$$

the equality with zero representing the eq. of a circle (Fig. 3) having the center


Fig. 3


Fig. 4
in $M(0, \beta C+\gamma / 2 \beta)$ and the radius $\sqrt{\beta^{2} C^{2}+\gamma^{2} / 4 \beta^{2}}$. Having in view relation (13) it results that the circle's center, $M$, can be situated both on semi-axis $y>0$ or $y<0$. In the same time, taking into account the notations (8) too, circle's (35) eq. may be written as

$$
\begin{gather*}
R_{2}^{2}\left(I_{m}\right)+X_{2}^{2}\left(I_{m}\right)-\left[2 C \mathfrak{I} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)+\frac{A_{22}^{2}}{\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)}\right] X_{2}\left(I_{m}\right)+  \tag{36}\\
+\frac{A_{22}^{4}}{2\left[\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}+C A_{22}^{2}=0,
\end{gather*}
$$

having the center in $M\left[0, C \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)-A_{22}^{2} / 2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]$ and the radius $\sqrt{C^{2}\left[\Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}-A_{22}^{2} / 4\left[\Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}$. At the same time relations (33) and (34) become

$$
\begin{gather*}
y_{2}^{\prime}, y_{2}^{\prime \prime}=C \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)+\frac{A_{22}^{2}}{2 \Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)} \pm  \tag{3}\\
\pm \sqrt{4 C^{2}\left[\Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}-A_{22}^{4} /\left[\Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}},
\end{gather*}
$$

respectively

$$
\begin{equation*}
C \geq \frac{A_{22}^{2}}{2\left[\Im m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}>0 . \tag{38}
\end{equation*}
$$

Since $x$ and $y$ have the significances of a resistance, respectively of a reactance, it is evidently that only the half circle situated in the semi-plane $x>0$ has a physical meaning. This half of circle may be considered as representing the geometric-locus diagram of the complex impedance $\underline{Z}_{2}\left(I_{m}\right)$ corresponding to the extreme values of complex transfer impedance, $\underline{Z}_{m}$, when the LNT's fundamental parameters satisfy relation $\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=0$.
b) Case $\beta=0\left(\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=0\right)$. This situation is realized when $Q_{20}=$ $=0$. Considering the LNT's equivalent scheme in T represented in Fig. 2, this case corresponds to the situation when complex impedance $\zeta_{2}$ and $\zeta_{3}$ have equal and of opposite sign reactances $\left(\mathfrak{J} m\left(\underline{\zeta}_{2}\right)=-\mathfrak{J} m\left(\underline{\zeta}_{3}\right)\right)$. In this particular case the differential eq. (14) becomes

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} y}+\frac{y(2 \alpha x+\gamma)}{\alpha\left(x^{2}-y^{2}\right)+\gamma x}=0, \tag{3}
\end{equation*}
$$

similar to the differential eq. (18). Consequently, using an analogous proceeding as in the previous particular case, is possible to integrate differential eq. (39) obtaining

$$
\begin{equation*}
y=\sqrt{C^{\prime}(2 \alpha x+\gamma)-\frac{1}{4 \alpha^{2}}\left[(2 \alpha x+\gamma)^{2}+\gamma^{2}\right]}, \tag{40}
\end{equation*}
$$

where $C^{\prime}$ is an integration constant. Because $y$ represents a reactance (see rel. (8)) it must be a real quantity so that the inequality

$$
\begin{equation*}
C^{\prime}(2 \alpha x+\gamma)-\frac{1}{4 \alpha^{2}}\left[(2 \alpha x+\gamma)^{2}+\gamma^{2}\right] \geq 0 \tag{41}
\end{equation*}
$$

must be fulfilled, which is equivalent with the inequality

$$
\begin{equation*}
x^{2}-\left(2 \alpha C^{\prime}-\frac{\gamma}{\alpha}\right) x-\gamma C^{\prime}+\frac{\gamma^{2}}{2 \alpha^{2}} \leq 0 \tag{42}
\end{equation*}
$$

The roots of the trinomial from the left side of inequality (42) are

$$
\begin{equation*}
x^{\prime}, x^{\prime \prime}=\alpha C^{\prime}-\frac{\gamma}{2 \alpha} \pm \frac{1}{2} \sqrt{2 \alpha^{2} C^{\prime 2}-\frac{\gamma^{2}}{\alpha^{2}}} . \tag{43}
\end{equation*}
$$

The integration constant, $C^{\prime}$, satisfies the inequality

$$
\begin{equation*}
C^{\prime} \geq \frac{\gamma}{2 \alpha^{2}}>0 \tag{44}
\end{equation*}
$$

where notations (13) were taken into account.
Relation (40) can be written, more advantageously, as

$$
\begin{equation*}
x^{2}+y^{2}-\left(\frac{\gamma}{\alpha}-2 \alpha C^{\prime}\right) x+\frac{\gamma^{2}}{2 \alpha^{2}}-\gamma C^{\prime}=0 \tag{45}
\end{equation*}
$$

which represents the eq. of a circle (Fig. 4) having the center in $M^{\prime}\left(\gamma / 2 \alpha-\alpha C^{\prime}, 0\right)$ and the radius $\sqrt{\alpha^{2} C^{\prime 2}-\gamma^{2} / 4 \alpha^{2}}$. Having in view inequalities (43) it results that the circle's center, $M^{\prime}$, is situated constantly on the axis $x<0$.

In this case too, having in view that $x$ and $y$ have the significances of a resistance, respectively of a reactance, only the circle's arc situated in the halfplane $x \geq 0$ have a physical meaning. This circle's arc constitutes, properly, the complex impedance's $\underline{Z}_{2}\left(I_{m}\right)$ geometric-locus diagram wich corresponds to the extreme values of transfer complex impedance's modulus, $Z_{m}$, when the LNT's fundamental parameters satisfy relation $\mathfrak{I} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)=0$.

Having in view the relations (8) and (13) significations eq. (45) may be written as

$$
\begin{gather*}
R_{2}^{2}\left(I_{m}\right)+X_{2}^{2}\left(I_{m}\right)-\left[\frac{A_{22}^{2}}{\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)}-2 C^{\prime} \mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right] R_{2}\left(I_{m}\right)+  \tag{46}\\
+\frac{A_{22}^{4}}{2\left[\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}-C^{\prime} A_{22}^{2}=0,
\end{gather*}
$$

having the center in $M^{\prime}\left[A_{22}^{2} / 2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)-C^{\prime} \mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right), 0\right]$ and the radius $\sqrt{C^{\prime 2}\left[\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}-A_{22}^{4} /\left[\mathfrak{J} m\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}$. In the same time relations and (44) become

$$
\begin{align*}
& R_{2}^{\prime}\left(I_{m}\right), R_{2}^{\prime \prime}\left(I_{m}\right)=C^{\prime} \mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)-\frac{A_{22}^{2}}{2 \Re e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)} \pm  \tag{47}\\
& \pm \frac{1}{2} \sqrt{4 C^{\prime 2}\left[\mathfrak{R} e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}-A_{22}^{4} /\left[\mathfrak{R e}\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}
\end{align*}
$$

respectively

$$
\begin{equation*}
C^{\prime} \geq \frac{A_{22}^{2}}{2\left[\mathfrak{R} e\left(\underline{A}_{21} \underline{A}_{22}^{*}\right)\right]^{2}}>0 . \tag{38}
\end{equation*}
$$

## 5. Conclusions

1. The differential equation satisfied by function $X_{2}\left(R_{2}\right)$ is established, where $\underline{Z}_{2}=R_{2}+\mathrm{j} X_{2}$ is the nonlinear, inertial receiver's complex impedance of a linear and non-autonomous two-port (in a restreint sense), in harmonic steadystate, so that the two-port's transfer complex impedance's modulus have extreme values
2. The established differential equation, which is nonlinear of first order, is integrated analytically in two particular cases. In each case the equation $X_{2}\left(R_{2}\right)$ represents a circle which is, in the half-plane $R_{2} \geq 0$, the geometric-locus diagram of the receiver's complex impedance, $\underline{Z}_{2}$, corresponding to the extreme values of the two-port's transfer complex impedance, $\underline{Z}_{m}$, for different values of the secondary current amplitude (and, implicitely, of the primary voltage amplitude).

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## IMPEDANȚA DE TRANSFER A UNUI CUADRIPOL LINIAR CU RECEPTOR NELINIAR

(Rezumat)
Se stabileşte ecuația diferențială, neliniară, de primul ordin, satisfăcută de funcția $X_{2}\left(R_{2}\right)$, unde $\underline{Z}_{2}=\mathscr{R}_{2}+\mathrm{j} X_{2}$ este impedanța complexă a receptorului neliniar, inerțial şi pasiv, a unui cuadripol (în sens restrâns) liniar şi neautonom, în regim permanent armonic, astfel încât modulul impedanței de transfer a cuadripolului să aibă o valoare extremă.

Ecuația diferențială stabilită se integrează în două cazuri particulare, în care aceasta este de tip Bernoulli, permițând obținerea unei soluții analitice.


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